

Automatic Seismic Interpretation Networks

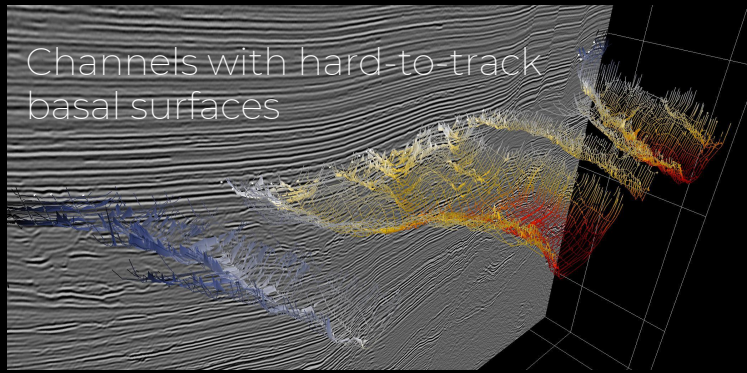
FORCE ML symposium 2019

Dimitrios Oikonomou, Giorgos Stefos, Thodoris Papadopoulos, Steve Purves, Nan Duan
Chalong Jaruwattanasaku, Behzad Alaei, Eirik Larsen*



The Geoscience Problem

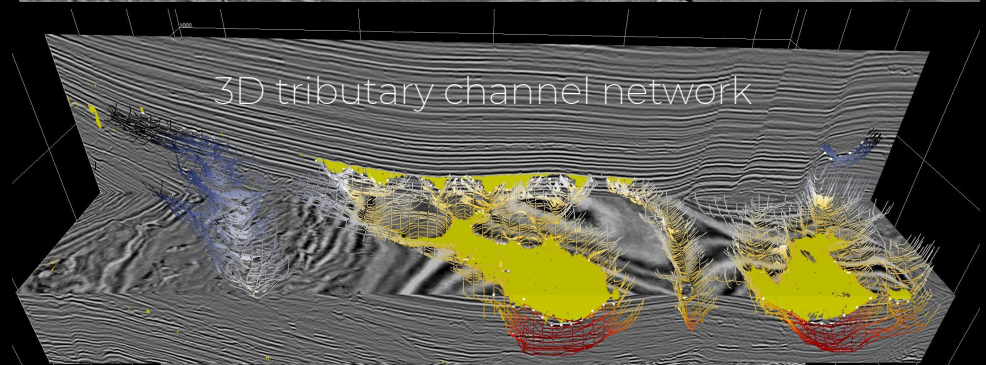
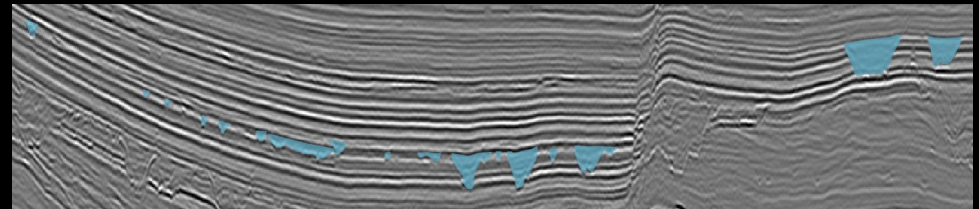
Interpret complex 3D geobodies
fast with minimal human input



Manual (point) interpretation:

- time consuming
- prone to errors

Manual 2D interpretation on 18 crosslines



Automatic Seismic Interpretation

Methodology followed

Methods & Parameters controlled:

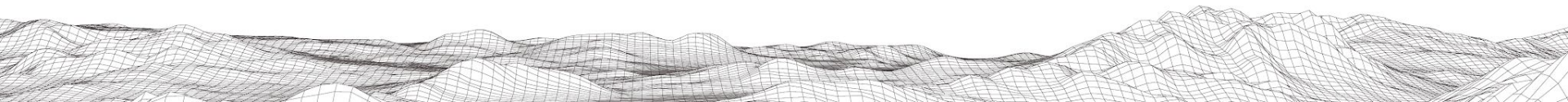
- Train - Split - Blind
- Training slices: 18 crosslines
- Blind slices: 2 crosslines
- Patch size: 256 x 256
- Random Noise: 1%
- Dropout: 0.2
- Epochs: 100

Architectures tested:

- Unet - Light Unet
- Segnet - Light Segnet
- PSP - Light PSP
- DeepLab3+ - Light DeepLab3+

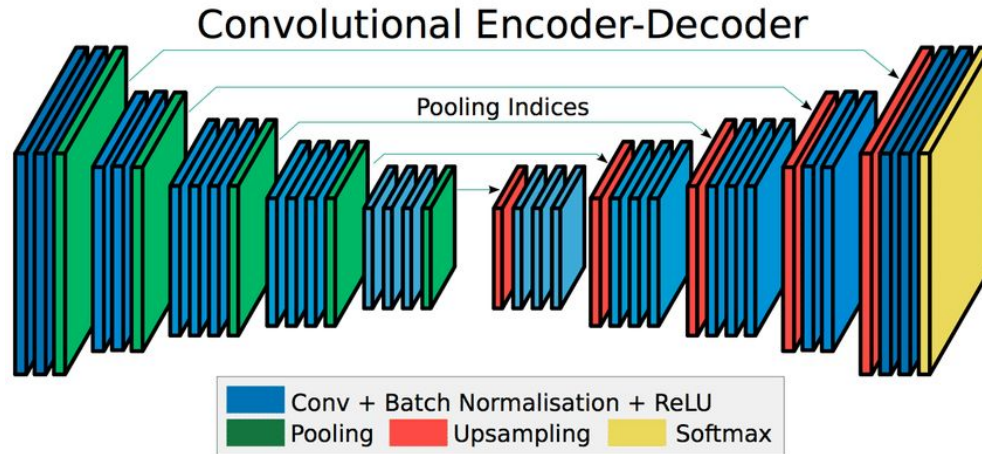
Loss functions:

- Weighted cross entropy
- Dice
- Jaccard



Segnet

Classic Segnet Architecture [1]



Year released: 2015

Benchmarks (VOC2012)[5] -Mean IOU: 0.599

Light - Segnet

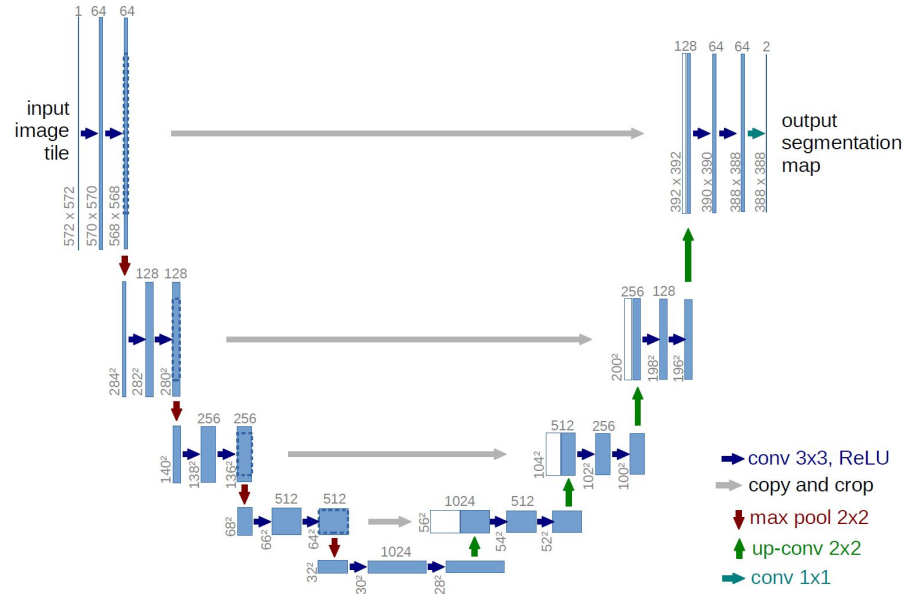
- Add/remove any number of layers
- Respectively customize filters on convolution layers

This results in full control over network depth and number of training parameters.



Unet

Classic Unet Architecture [2]



Year released: 2015

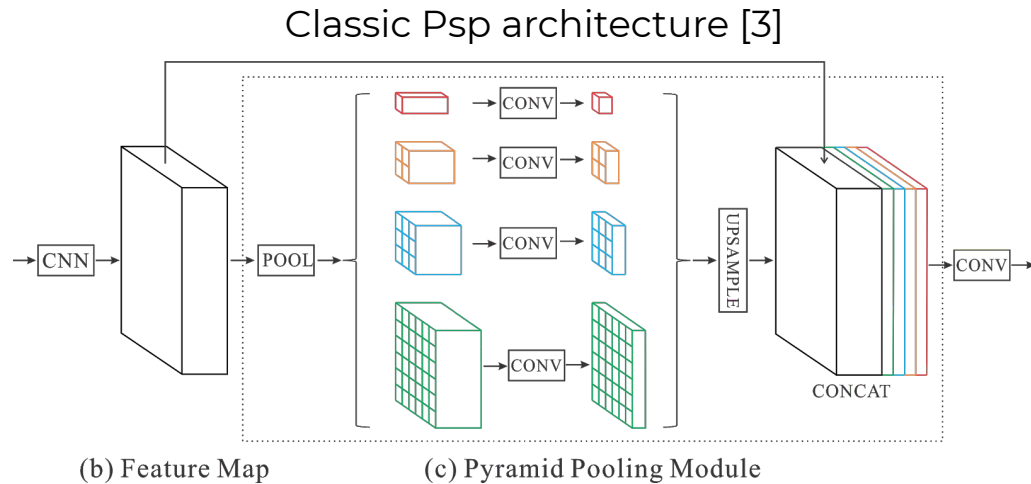
Benchmarks (ISBI cell tracking challenge) - Mean IOU: 0.775

Light Unet

- Add/remove any number of layers
- Respectively customize filters on convolution layers

This results in full control over network depth and number of training parameters.

Pyramid Scene Parsing Network (Psp Net)

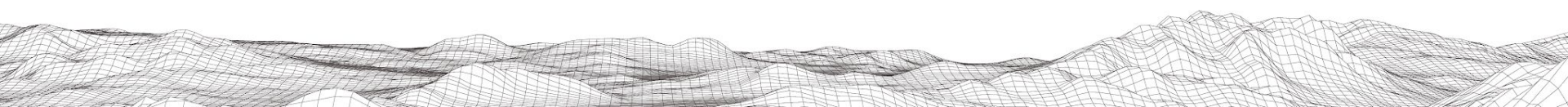


Light PSP

- During Feature Map phase usually a Resnet (huge) is used so we:
 - Reduce Resnet's overall size
- During Pyramid Pooling Module one can modify the dimensions of the sub-regions

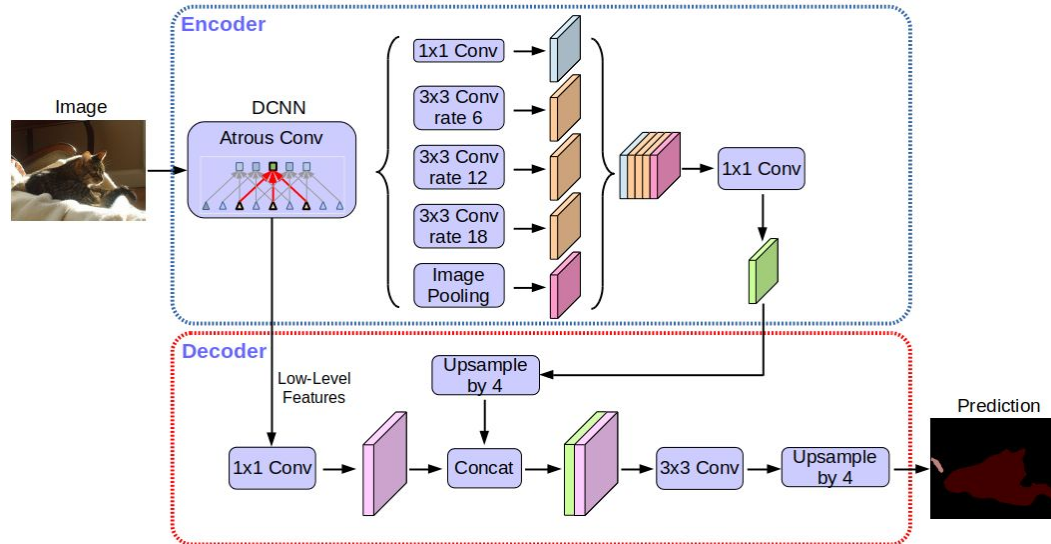
Year released: 2017

Benchmarks (VOC2012) -Mean IOU: 85.4



DeepLab v3+

Classic DeepLabV3+ architecture [4]



Year released: 2018

Benchmarks (VOC2012) -Mean IOU: 87.8

Light Deeplab

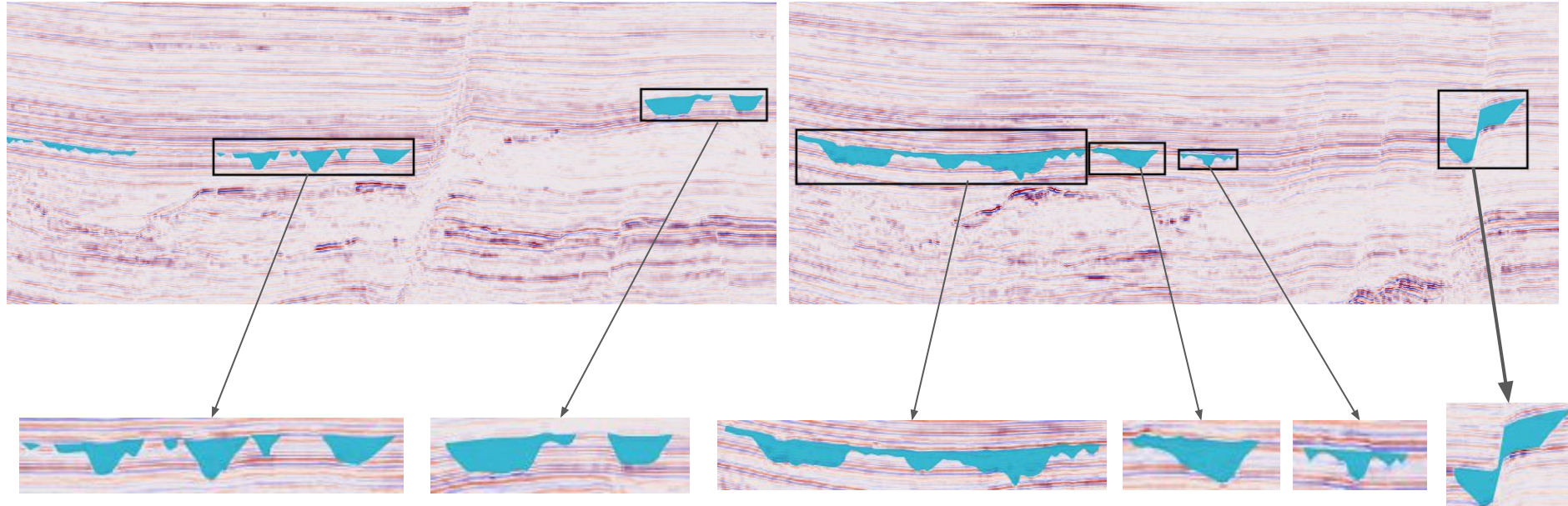
Same as the Psp Net one can use smaller CNN's as feature extractors and different Convolution dilation rates (Atrous Conv)



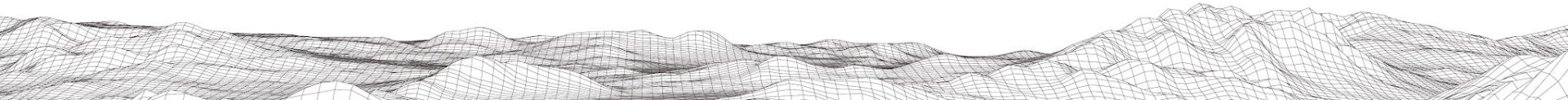
Truth Labels on Blind Test Slices

Blind 1

Blind 2



Human expert's seismic interpretation (labels) are regarded as ground truth

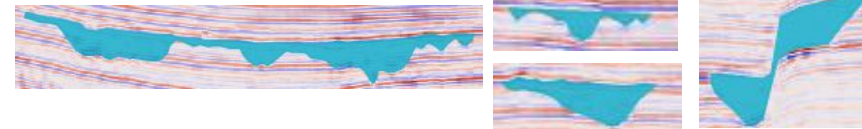


Segnet results

Blind 1

Blind 2

Truth



Full Segnet
(~29M parameters)



IoU: 0.624



IoU: 0.709

Light Segnet
(~2M parameters)



IoU: 0.701



IoU: 0.788

Light Segnet
(~300K parameters)



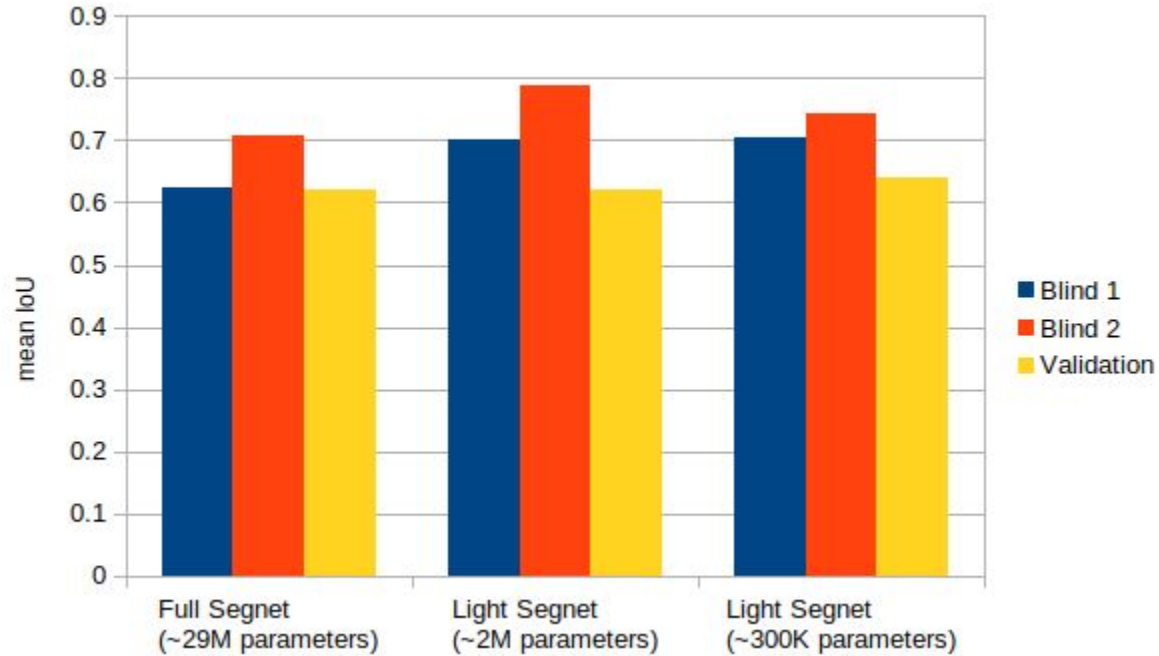
IoU: 0.704



IoU: 0.742



Segnet results

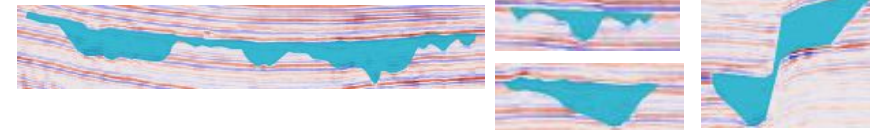


Light Segnet results against loss functions

Blind 1

Blind 2

Truth



Light Segnet
(~2M parameters)



IoU: 0.701



IoU: 0.788

Light Segnet
dice
(~2M parameters)



IoU: 0.633



IoU: 0.741

Light Segnet
jaccard
(~2M parameters)



IoU: 0.751



IoU: 0.710

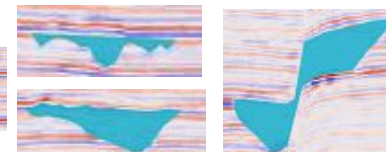
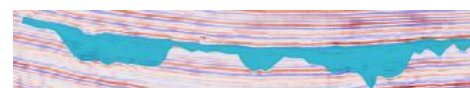


Unet results

Blind 1

Blind 2

Truth



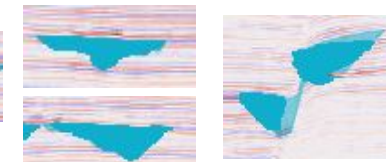
Full Unet
(~31M parameters)



IoU: 0.806



IoU: 0.855



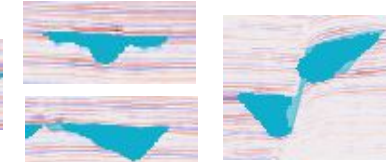
Light Unet
(~2M parameters)



IoU: 0.854



IoU: 0.875



Light Unet
(~300K parameters)



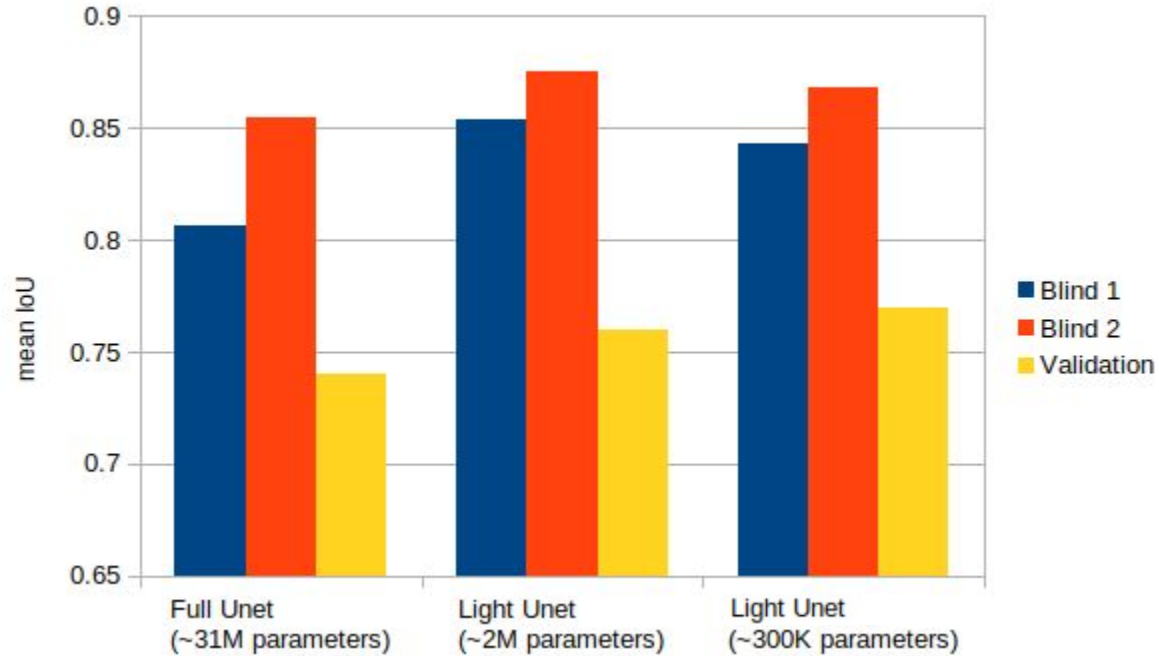
IoU: 0.843



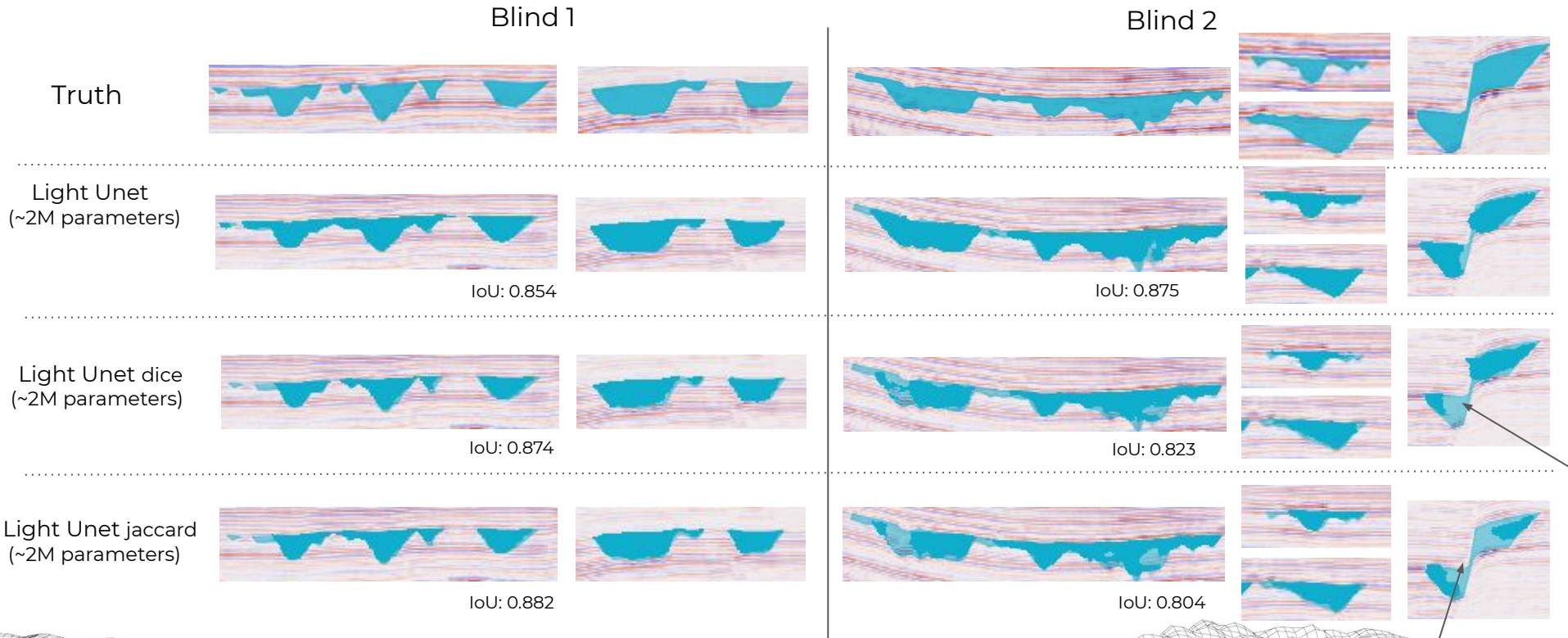
IoU: 0.868



Unet results



Light Unet results against loss functions

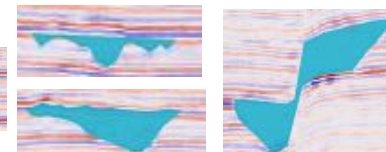


Psp results

Blind 1

Blind 2

Truth



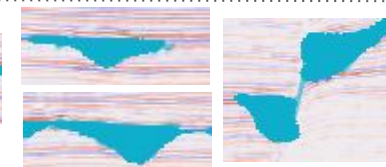
Full Psp
(~12M parameters)



IoU: 0.732



IoU: 0.834



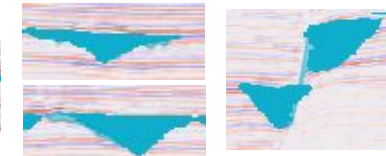
Light Psp
(~1.5M parameters)



IoU: 0.854



IoU: 0.875



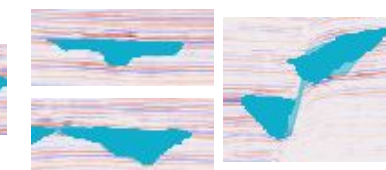
Light Psp
(~300K parameters)



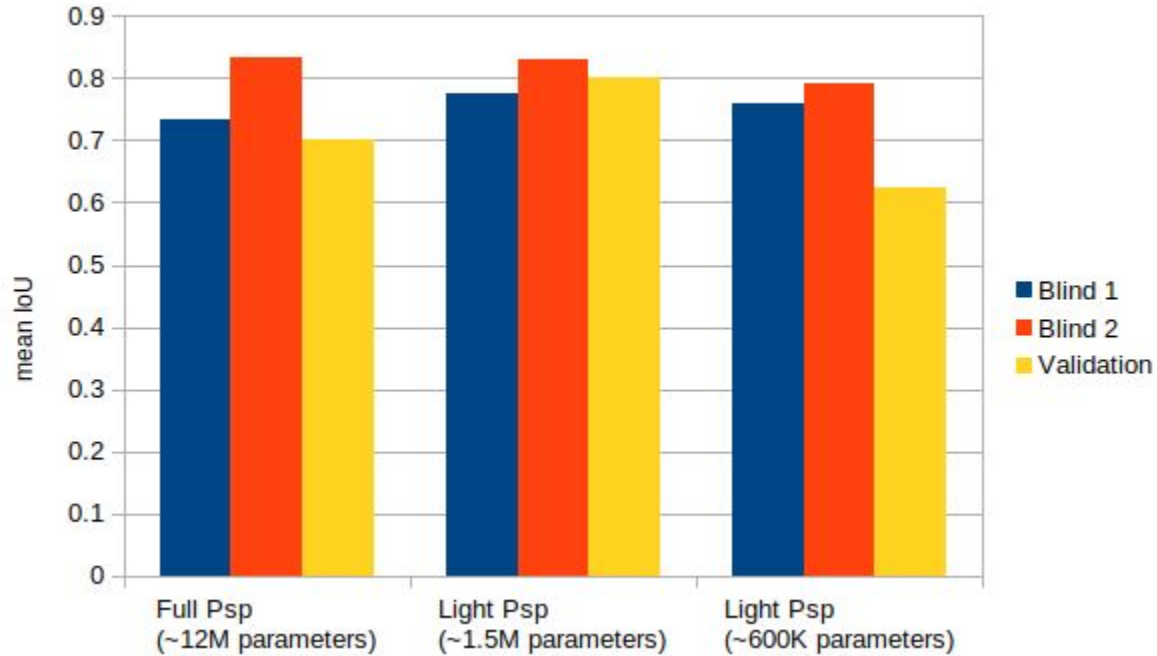
IoU: 0.843



IoU: 0.868



Psp net results

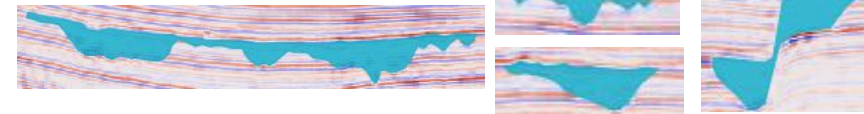


Light PSP results against loss functions

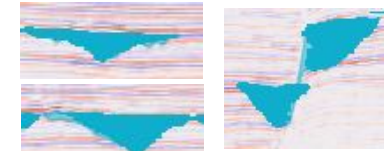
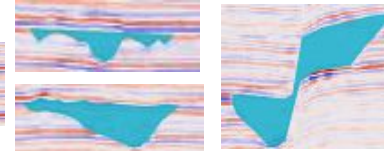
Blind 1

Blind 2

Truth



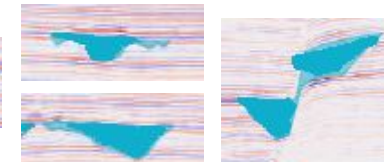
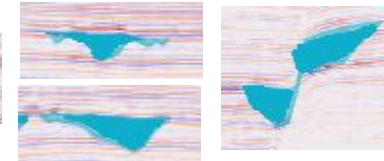
Light Psp
(~1.5M parameters)



IoU: 0.854

IoU: 0.875

Light Psp dice
(~1.5M parameters)



IoU: 0.856

IoU: 0.863

Light Psp jaccard
(~600K parameters)



IoU: 0.861

IoU: 0.871

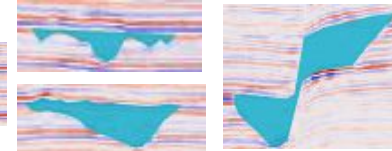


DeepLabv3+ results (Xception feature extractor)

Blind 1

Blind 2

Truth



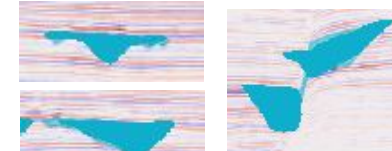
Full DeeplabV3+
(~41M parameters)



IoU: 0.817



IoU: 0.851



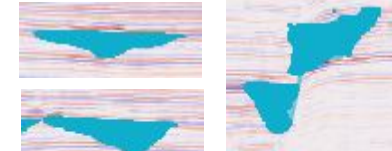
Light DeeplabV3+
(~1.5M parameters)



IoU: 0.799



IoU: 0.827



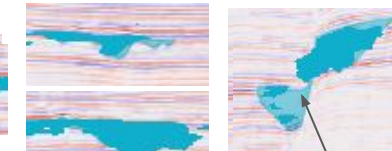
Light DeeplabV3+
(~650K parameters)



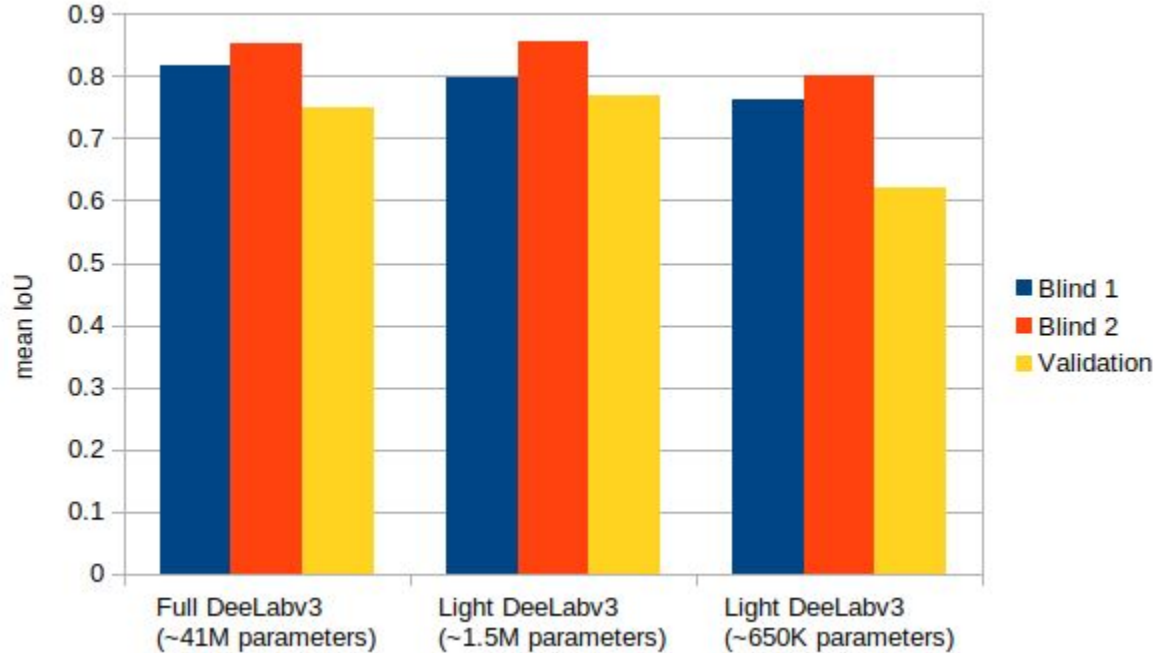
IoU: 0.764



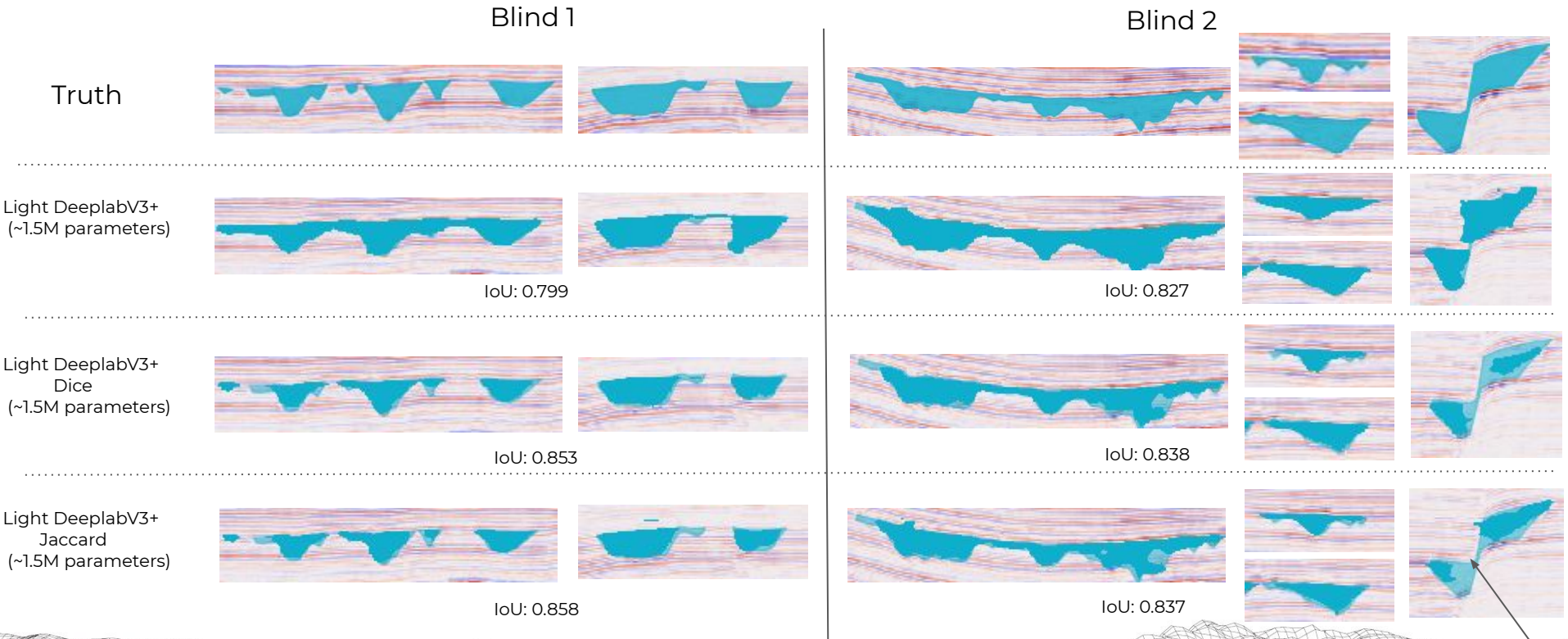
IoU: 0.802



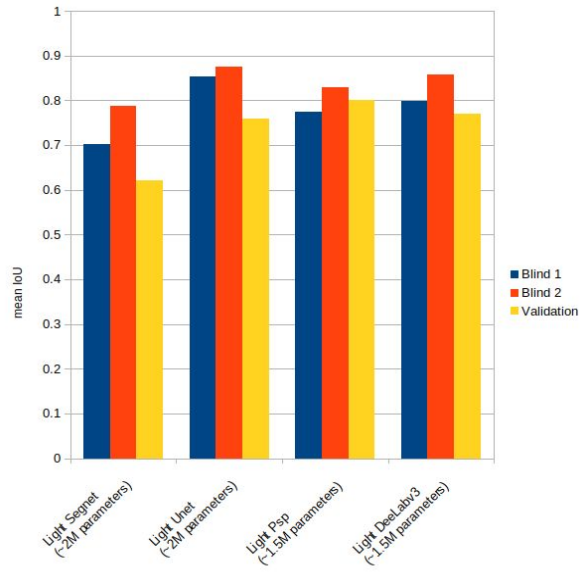
DeepLabv3+ results



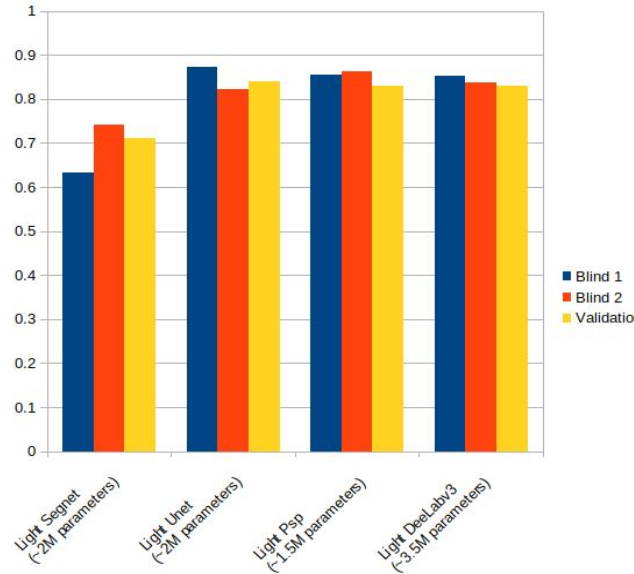
Light DeepLabv3+ results against loss functions



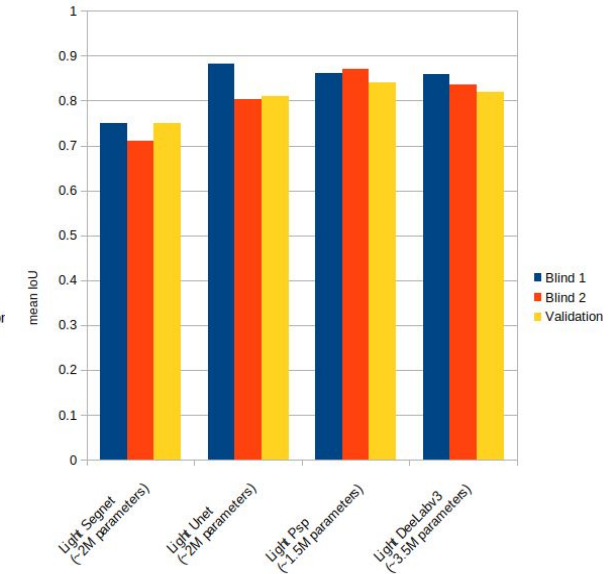
Comparison of light networks vs Loss



Weighted
Categorical Crossentropy



Dice



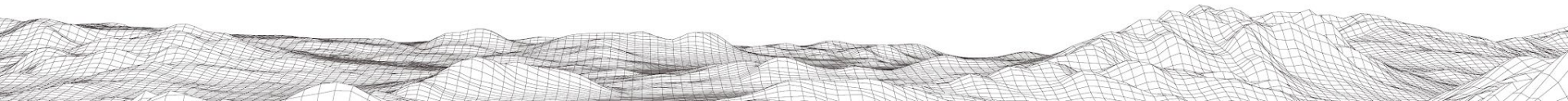
Jaccard



Conclusions Architectures, Data driven

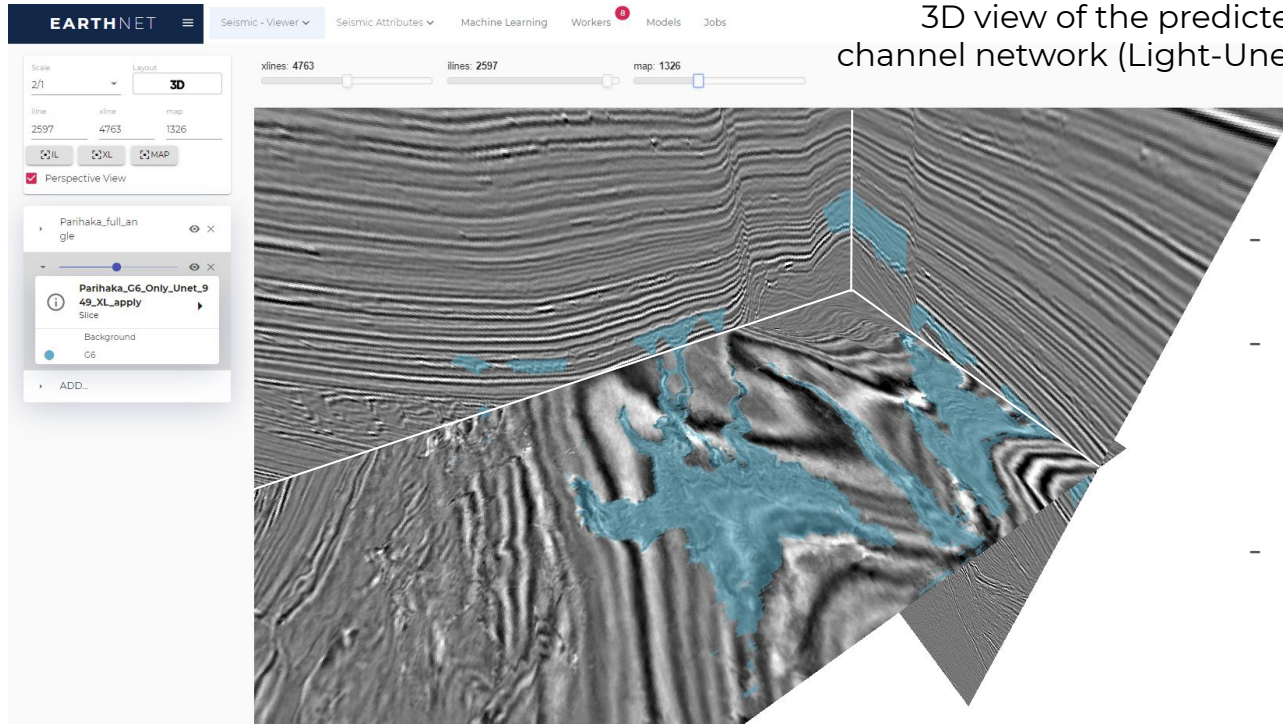
- On limited dataset large (public) networks tend to overfit
- Large networks do not guarantee better performance
- Revisit results obtained by Segnet architectures
- Smaller networks easier (and cheaper) to train
- Weighted Cross Entropy Loss slightly tends to overestimate volumes of unbalanced class (channels in the specific problem)
- Dice and Jaccard Loss slightly tends to underestimate volumes of unbalanced class

It is important to check network size with respect of the available labels

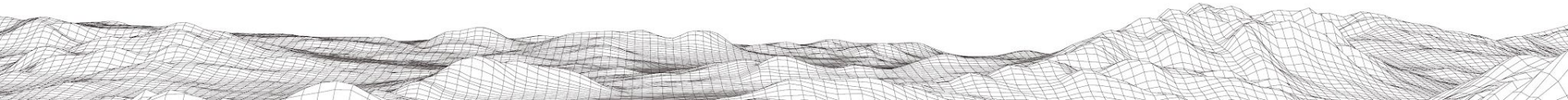


Conclusions, G&G

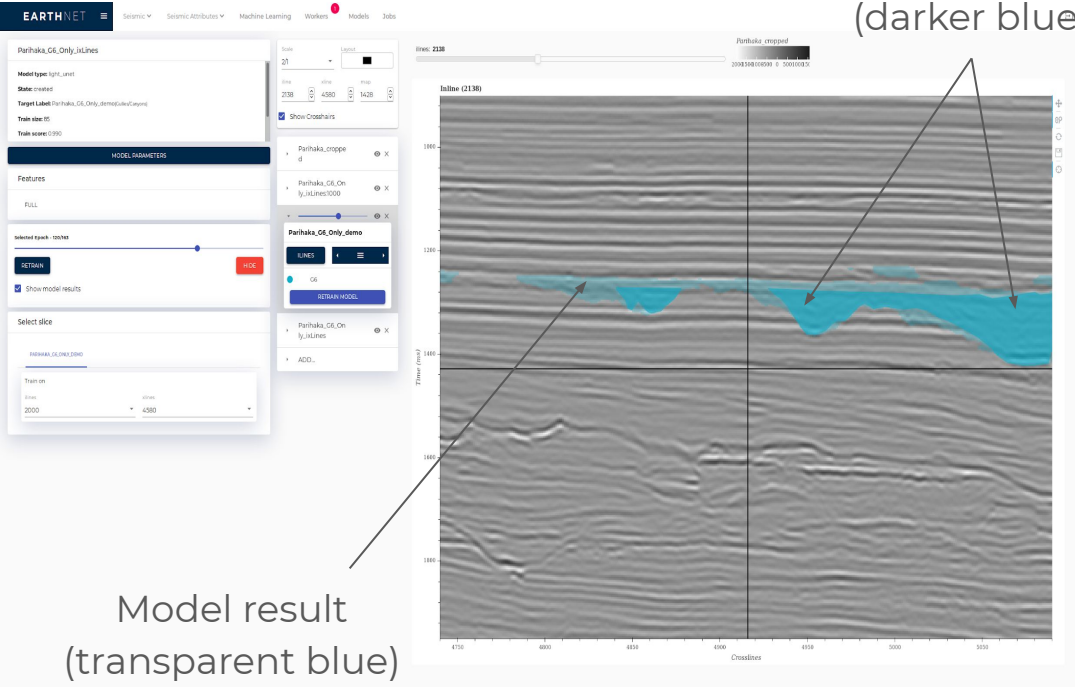
3D view of the predicted channel network (Light-Unet)



- ASI reduces interpretation cycle time
- ASI can improve quality of interpretation of very complex geological objects
- ASI 3D output can be used in for 3D geological models



Conclusions, G&G



Interactive labeling

- Model seems to predict 'better' than the labeler in some slices
- Obtaining True labels is a challenge, but key in order to train properly
- Interactive approach gives an effective suggestion for the labeller to make a decision.
- With the real time helping from DNN, the labeller can resolve challenges in complex areas
- DNN architectures smooth out possible inconsistency in labels by minimizing a global loss

References

1. Vijay Badrinarayanan, Alex Kendall, Roberto Cipolla. SegNet: A Deep Convolutional Encoder-Decoder Architecture for Image Segmentation. arXiv:1511.00561v3, 2015
2. Olaf Ronneberger, Philipp Fischer, Thomas Brox. U-Net: Convolutional Networks for Biomedical Image Segmentation. arXiv:1505.04597, 2015
3. Hengshuang Zhao, Jianping Shi, Xiaojuan Qi, Xiaogang Wang, Jiaya Jia. Pyramid Scene Parsing Network. arXiv:1612.01105, 2017
4. Liang-Chieh Chen, Yukun Zhu, George Papandreou, Florian Schroff, Hartwig Adam. Encoder-Decoder with Atrous Separable Convolution for Semantic Image Segmentation. arXiv:1802.02611, 2018
5. PASCAL VOC Challenge performance evaluation, [Leaderboard link](#)

We greatly appreciate and acknowledge the contributions of our Petromaks2 Project Partners:

The Research Council of Norway, WintershallIDEA, Spirit Energy, Lundin, ConocoPhillips

