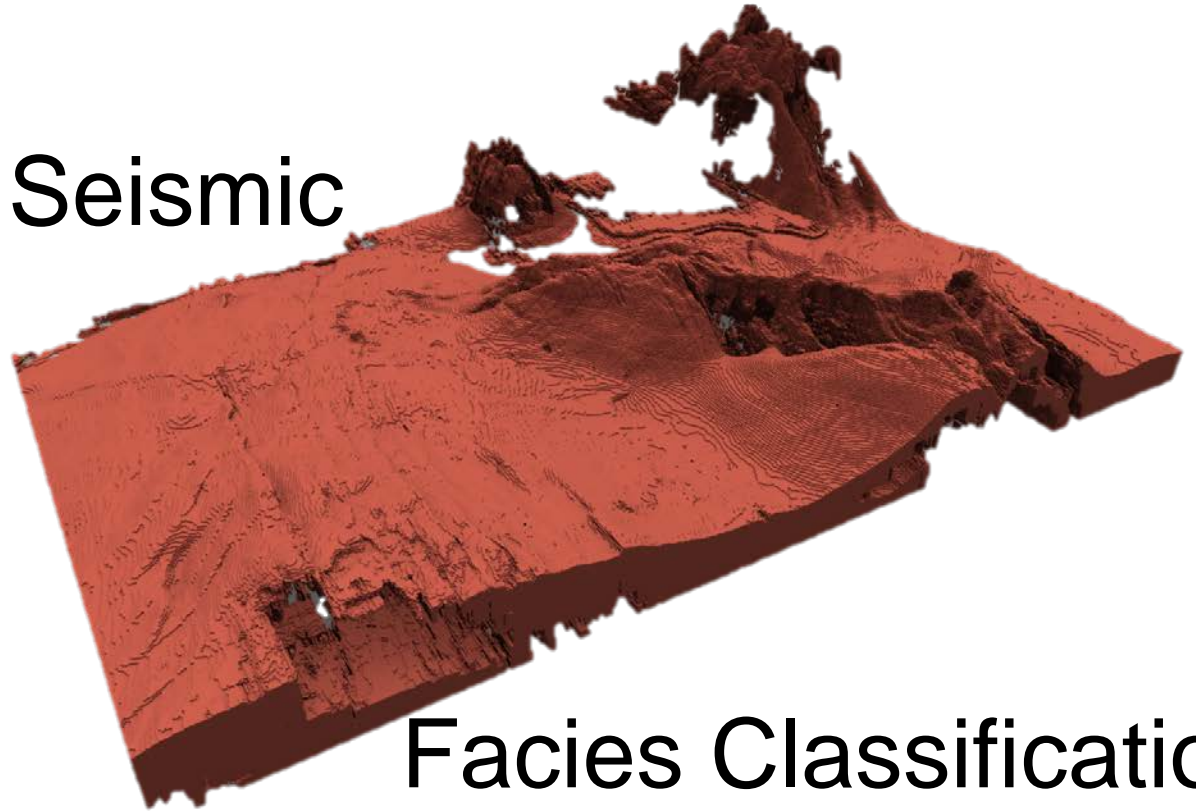


Probabilistic Seismic

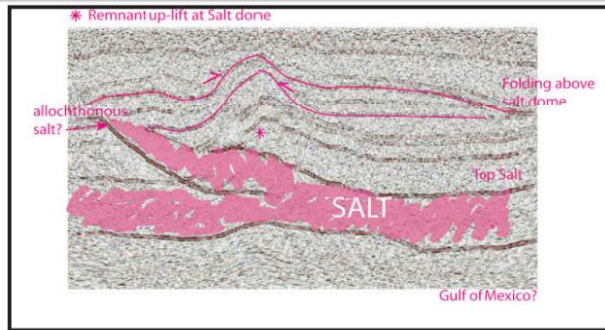


Facies Classification

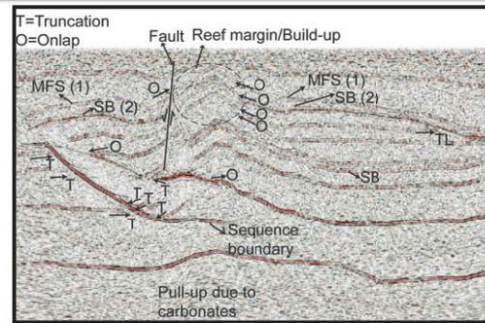
Lukas Mosser, Michael Steventon, Rodolfo Oliveira

lukas.mosser15@imperial.ac.uk, michael.steventon13@imperial.ac.uk, rodolfo.oliveira15@imperial.ac.uk

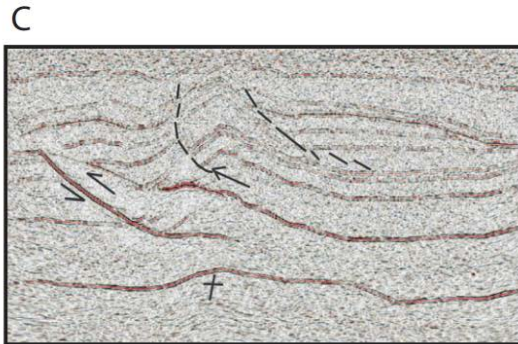
A Bayesian View on Seismic Interpretation



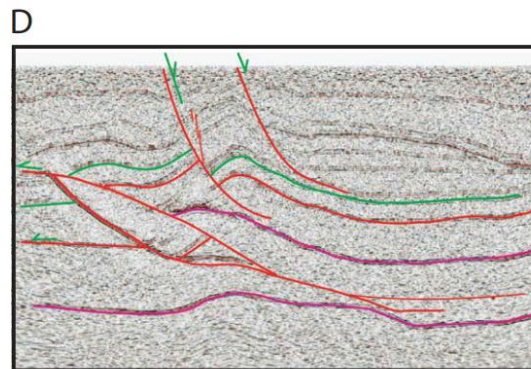
Student - PhD salt tectonics



Student - MSc sequence stratigraphy



+15 yrs - thrust expertise



+15 yrs - extensional expertise

Only 21% of G+G professionals got this correct

Bond et al (2007)

- Prior knowledge most important factor in the seismic interpretation
- Independent of data **prior** dominating term
- Machine Learning **can't** *interpret*
- But we can build models built on data and interpretations

Uncertainties in the seismic workflow

Data Acquisition

- Ambient Noise
- Acquisition Geometry
- Equipment Failure
- Tech Limitaitons

Data Processing

- Migration
- Time to Depth
- Noise Suppression
- Multiples
- Ghosting
- Down-sampling
- Etc.....

Data Interpretation

- Noise
- Artefacts
- Resolution
- Visual Representation



An interpreters, prior knowledge or lack of, bias, conceptual uncertainty can be an important source of error in the seismic workflow.

Types of Uncertainty

Aleatoric Uncertainty

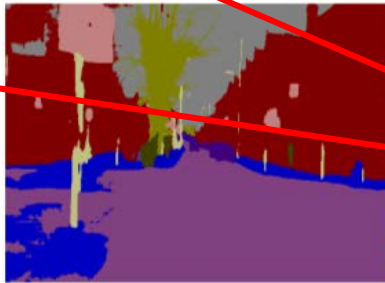
- Inherent “Noise” in Data
- **Not explained with more data**
- E.g. physical limits of data

Epistemic Uncertainty

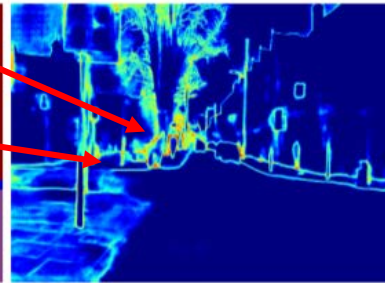
- Model Errors
- **Can be explained with more data**
- Seismic – often small data
Getting more data often not an option

Distant Objects may be occluded

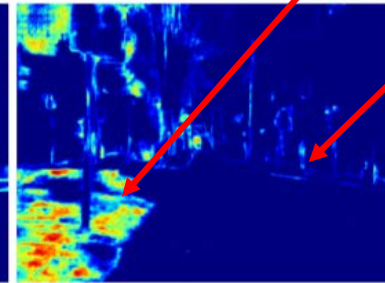
Boundary
Detection



(c) Semantic Segmentation



(d) Aleatoric Uncertainty



(e) Epistemic Uncertainty

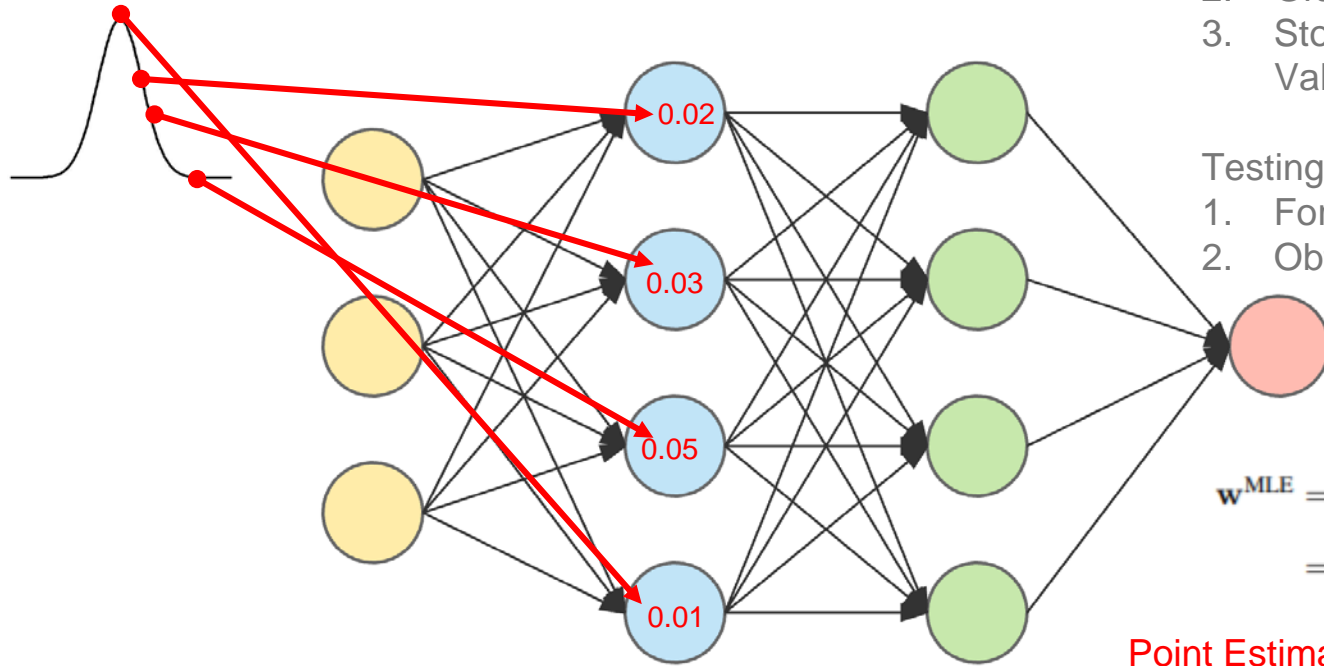
Textural Uncertainty

No Boundary issues

Distant Objects can't
be explained with more
data

From Deterministic to Bayesian Neural Networks

Weight Initialization



input layer

hidden layer 1

hidden layer 2

output layer

Training:

1. Initialize Weights
2. Gradient Descent
3. Stop when (Accuracy):
Val Measure < Train Measure

Testing:

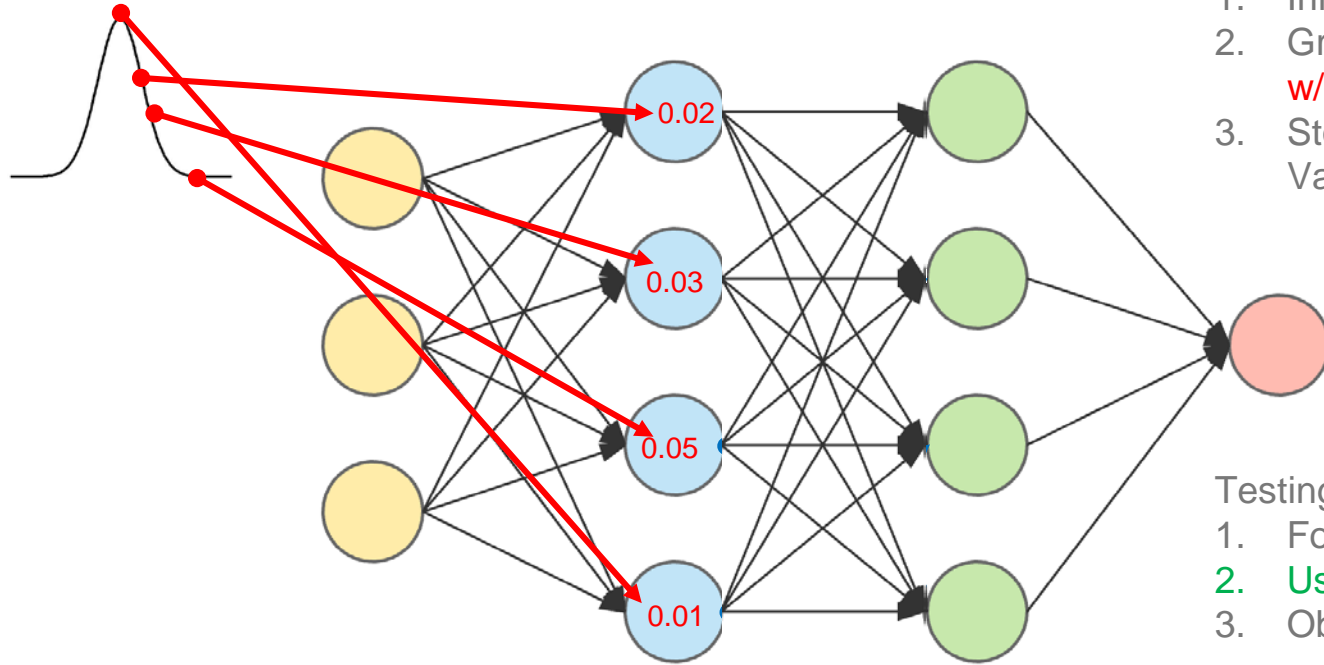
1. Forward pass test sample
2. Obtain prediction

$$\begin{aligned} \mathbf{w}^{\text{MLE}} &= \arg \max_{\mathbf{w}} \log P(\mathcal{D}|\mathbf{w}) \\ &= \arg \max_{\mathbf{w}} \sum_i \log P(\mathbf{y}_i|\mathbf{x}_i, \mathbf{w}). \end{aligned}$$

Point Estimates, no weight uncertainty

Deterministic Neural Networks with Dropout

Weight Initialization



input layer

hidden layer 1

hidden layer 2

output layer

Training:

1. Initialize Weights
2. Gradient Descent
w/ Zero weights at random
3. Stop when (Accuracy):
Val Measure < Train Measure

Testing:

1. Forward pass test sample
2. Use all weights (no dropout)
3. Obtain prediction

Point Estimates, no weight uncertainty

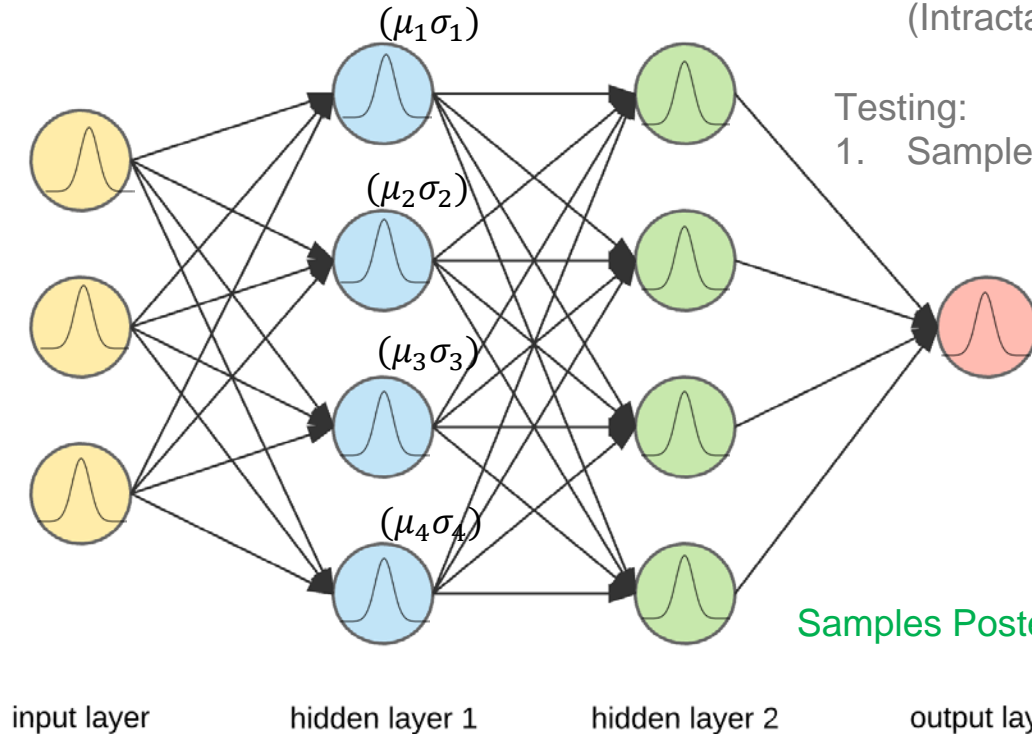
Bayesian Neural Networks

Training:

1. Select a distribution over weights
2. Posterior Inference of weight distributions
(Intractable in neural nets)

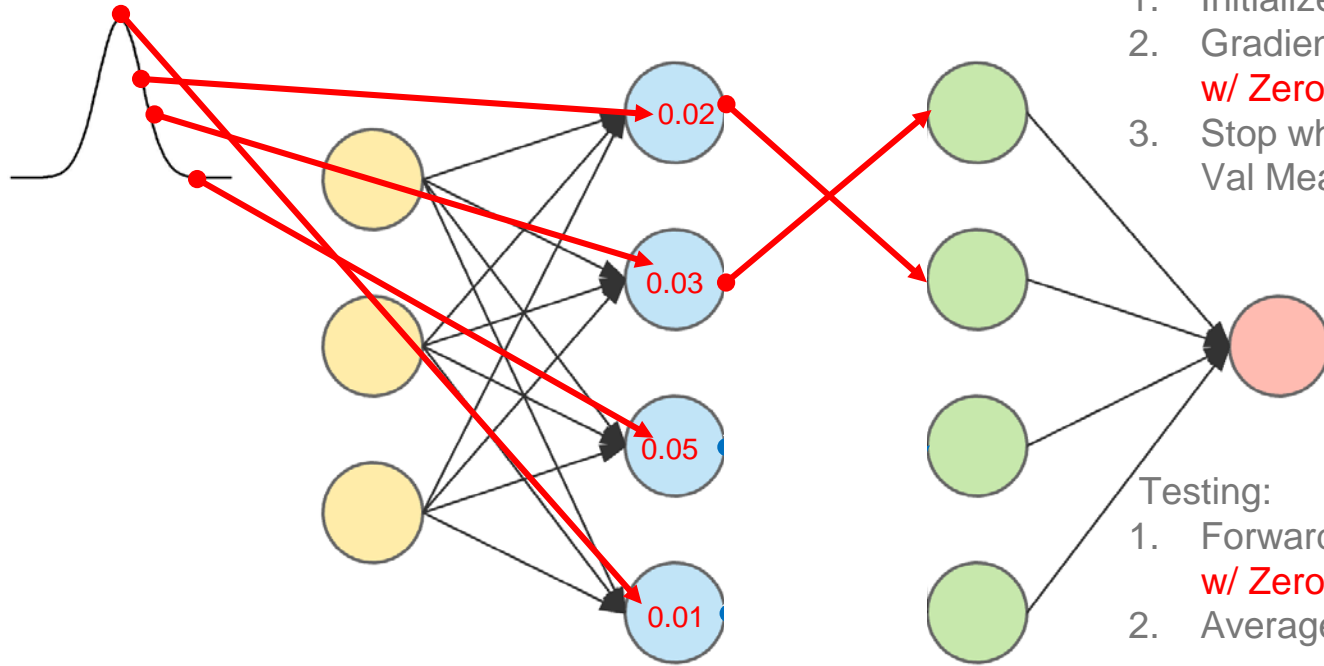
Testing:

1. Sample from posterior predictions



Approximate Posterior Inference by Dropout

Weight Initialization



input layer

hidden layer 1

hidden layer 2

Training:

1. Initialize Weights
2. Gradient Descent
w/ Zero weights at random
3. Stop when (Accuracy):
Val Measure < Train Measure

Testing:

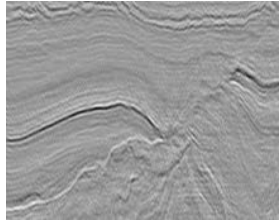
1. Forward pass test sample N times
w/ Zero weights at random
2. Average N Predictions

$$p(y = c | \mathbf{x}, \mathbf{X}, \mathbf{Y}) \approx \frac{1}{T} \sum_{t=1}^T \text{Softmax}(\mathbf{f}^{\widehat{\mathbf{W}}_t}(\mathbf{x}))$$

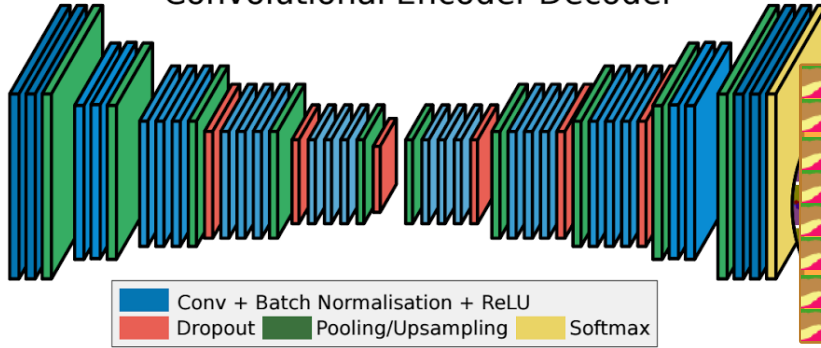
~ Samples Posterior Distribution of Weights

Model Architecture – Bayesian ConvNet: Segnet

Input Single Patch



Convolutional Encoder-Decoder



Stochastic Dropout Samples



mean

variance

Segmentation



Model Uncertainty



Dropout after every convolution operation!

1. Apply dropout at training time
2. Apply dropout at val/test time

Sample N Forward Predictions!

For each Patch in Inline/Xline

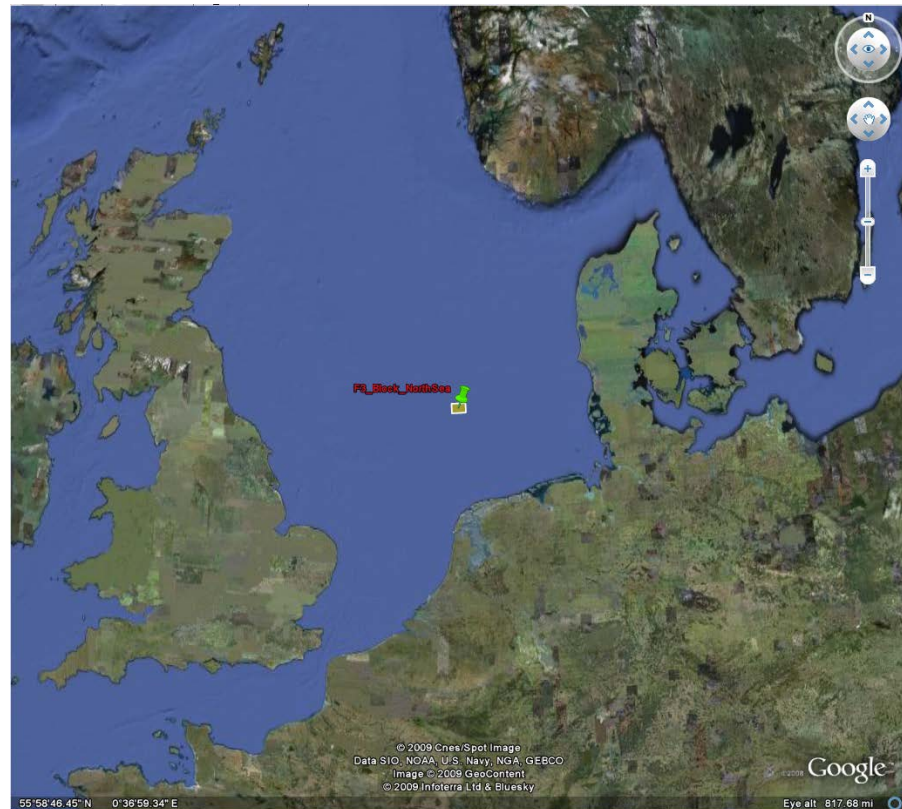
1. Average N Predictions
2. Compute Classwise Prediction Variance
-> Model Unvertainty -> Epistemic
Reassemble patches to obtain Inline/Xline

Dataset

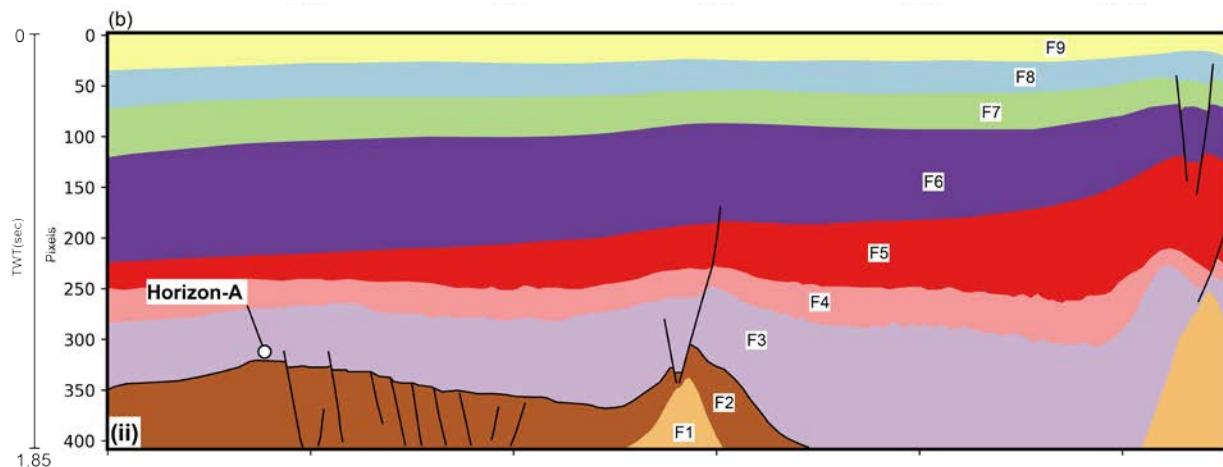
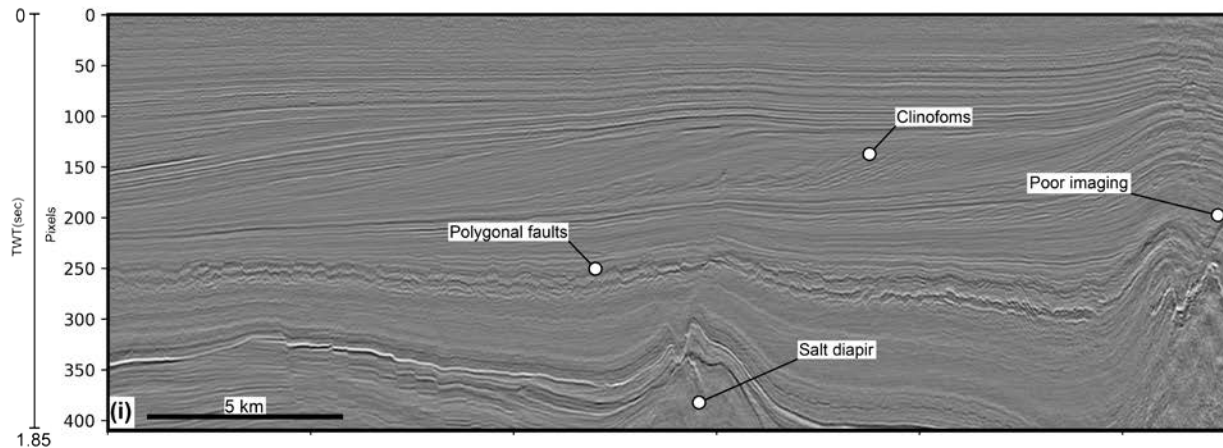
F3 Dataset – **OPEN ACCESS** – Dutch NLOG Database

<https://opendtect.org/osr/Main/NetherlandsOffshoreF3BlockComplete4GB>

Basin	Southern North Sea
Processing	Pre-Stack Time Migration
Area (km ²)	380
Bin Size (m)	25 × 25
Sampling Interval (ms)	4
Inline Range	100 - 750
Crossline Range	300 - 1250
Z Range (ms)	0 - 1850
Data Size	~1.0 GB
# of Training/Val Inlines	5 Training / 4 Validation



Seismic Facies Classification

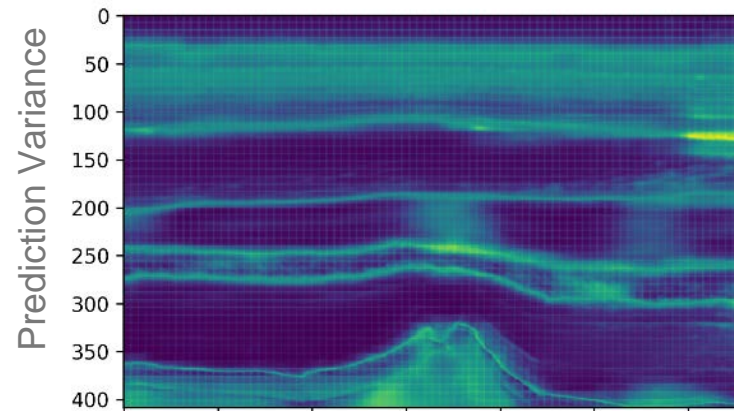


Facies	Seismic-based interpretation (no wells)
F10	<i>Biogenic Gas</i>
F9	<i>Acquisition footprint</i>
F8	<i>Bedded Sediments</i>
F7	<i>Bedded sediments</i>
F6	<i>Clinofoms (Deltaic)</i>
F5	<i>Bedded sediments</i>
F4	<i>Polygonal faulted sediments</i>
F3	<i>Bedded sediments</i>
F2	<i>Bedded sediments</i>
F1	<i>Salt tectonics</i>

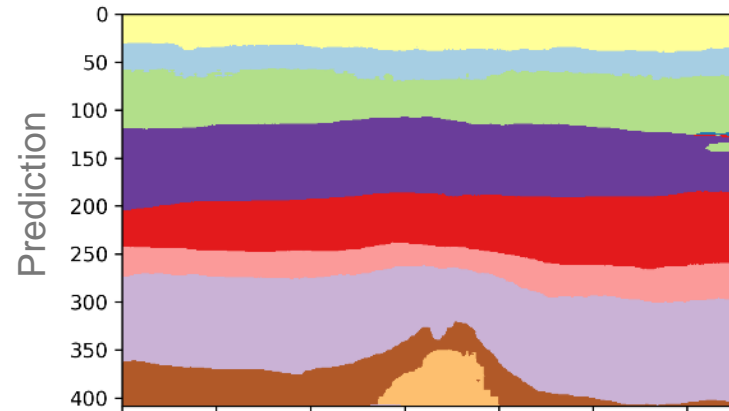
Validation Inline 4xx

*Gold Standard Annotation

Amplitude

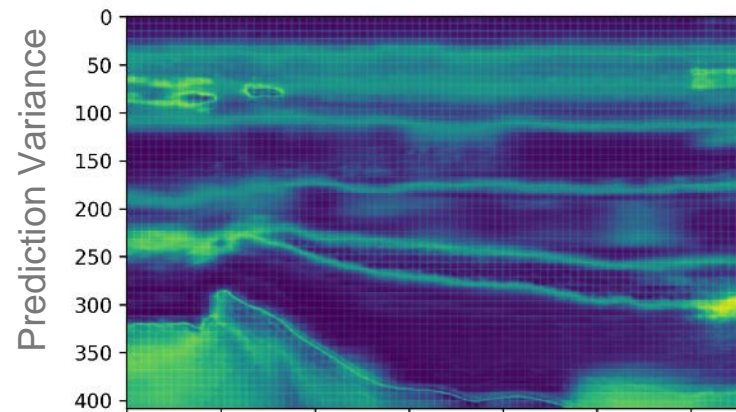


Ground Truth*

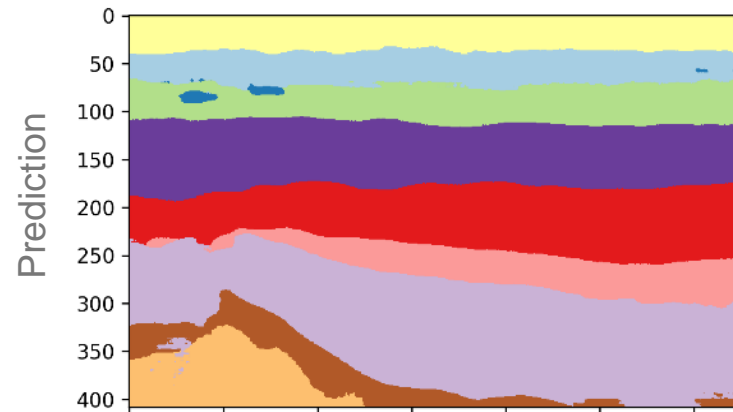


Validation Inline 6xx

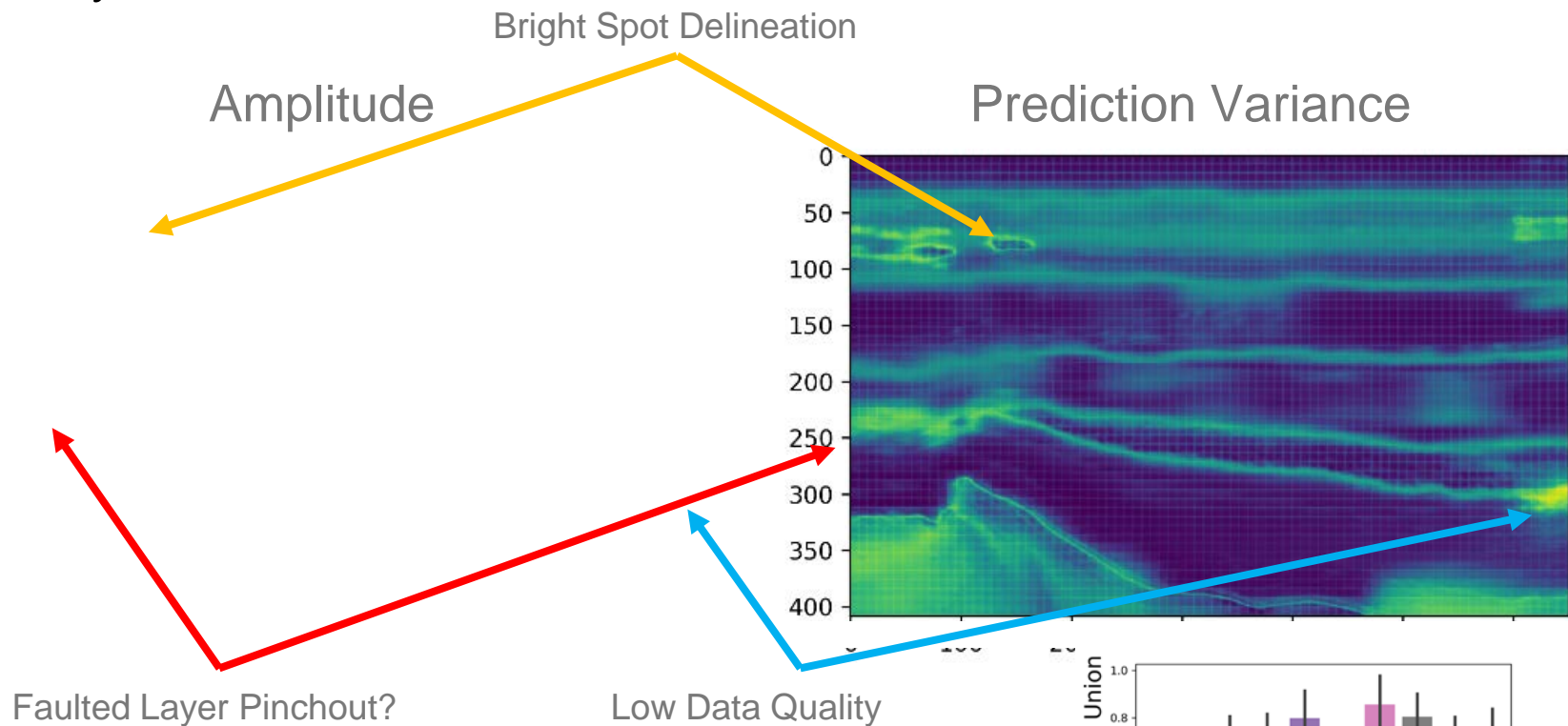
Amplitude



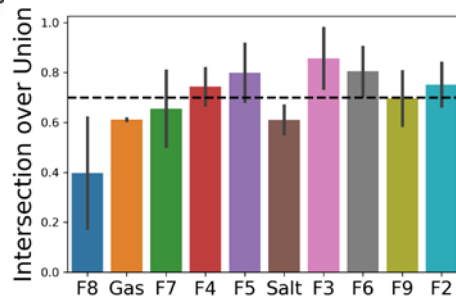
Ground Truth*



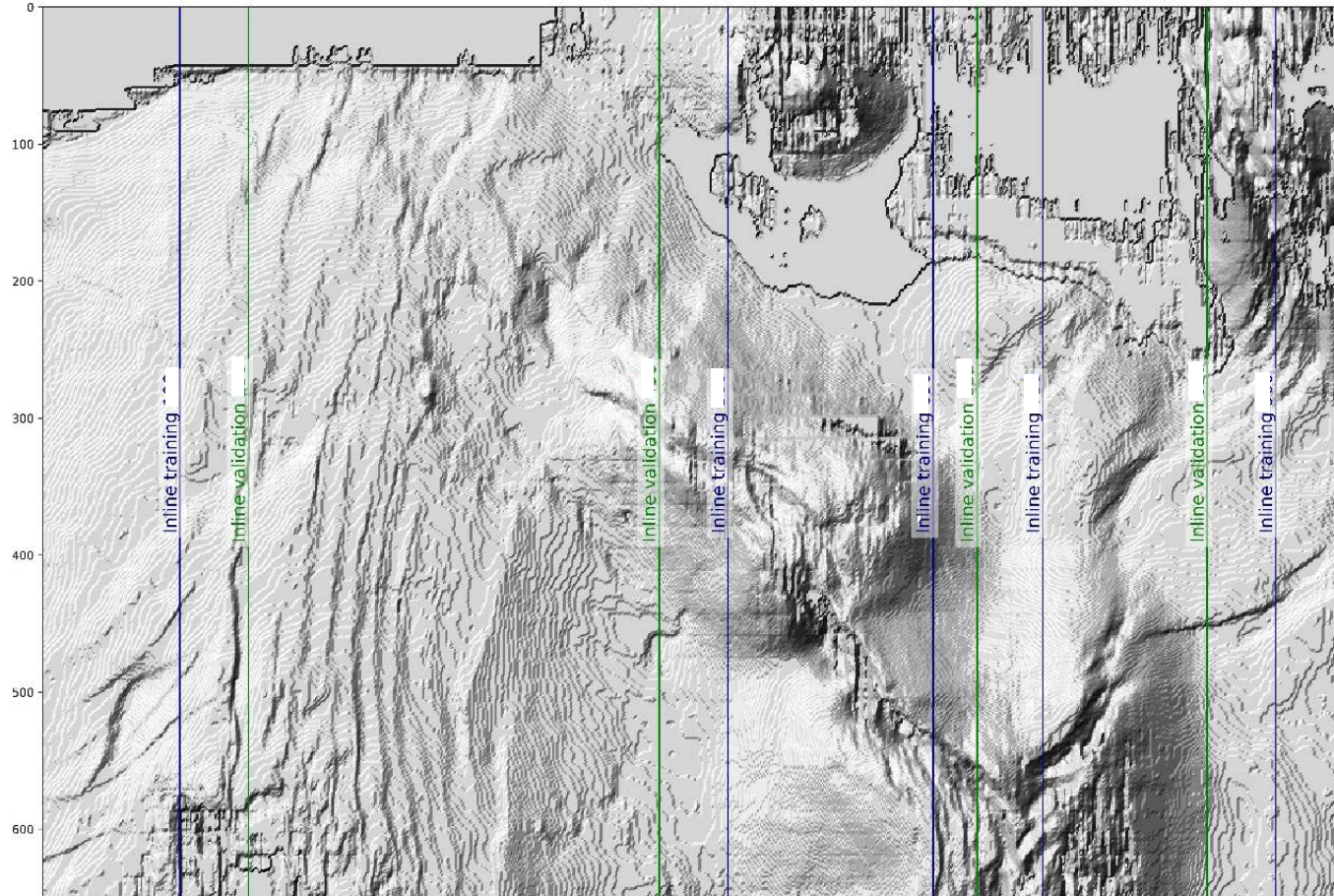
Uncertainty Features and Metrics



IoU Salt: 0.79 +/- 0.13
IoU Gas: 0.61 +/- 0.01
IoU Polygonal: 0.74 +/- 0.08

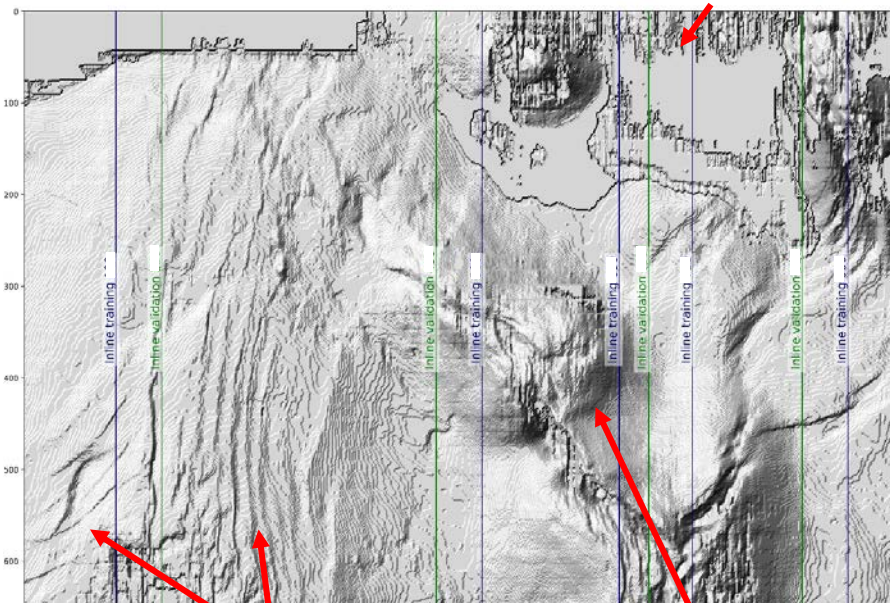


Top Salt Horizon



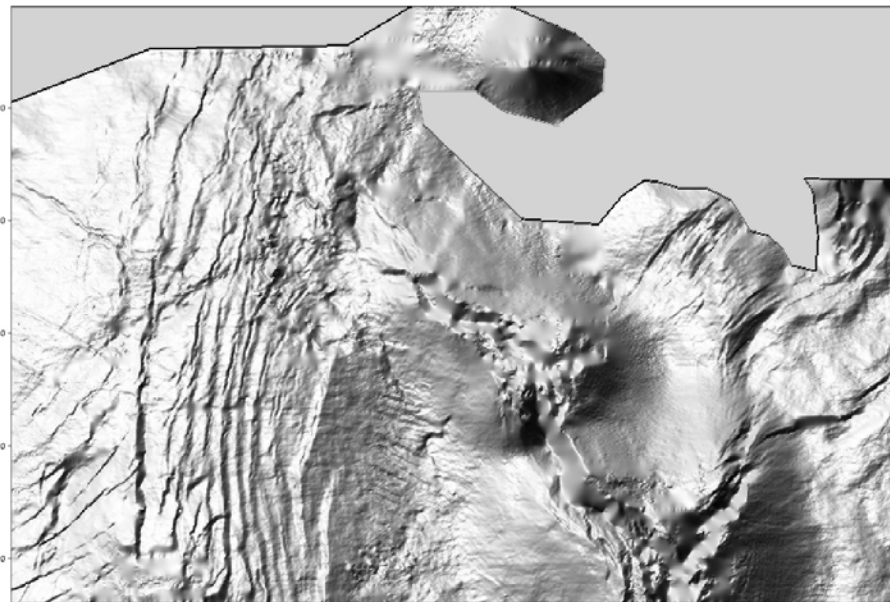
Top Salt: Bayesian CNN vs Human Interpreter

Data Quality issues lead to higher uncertainty



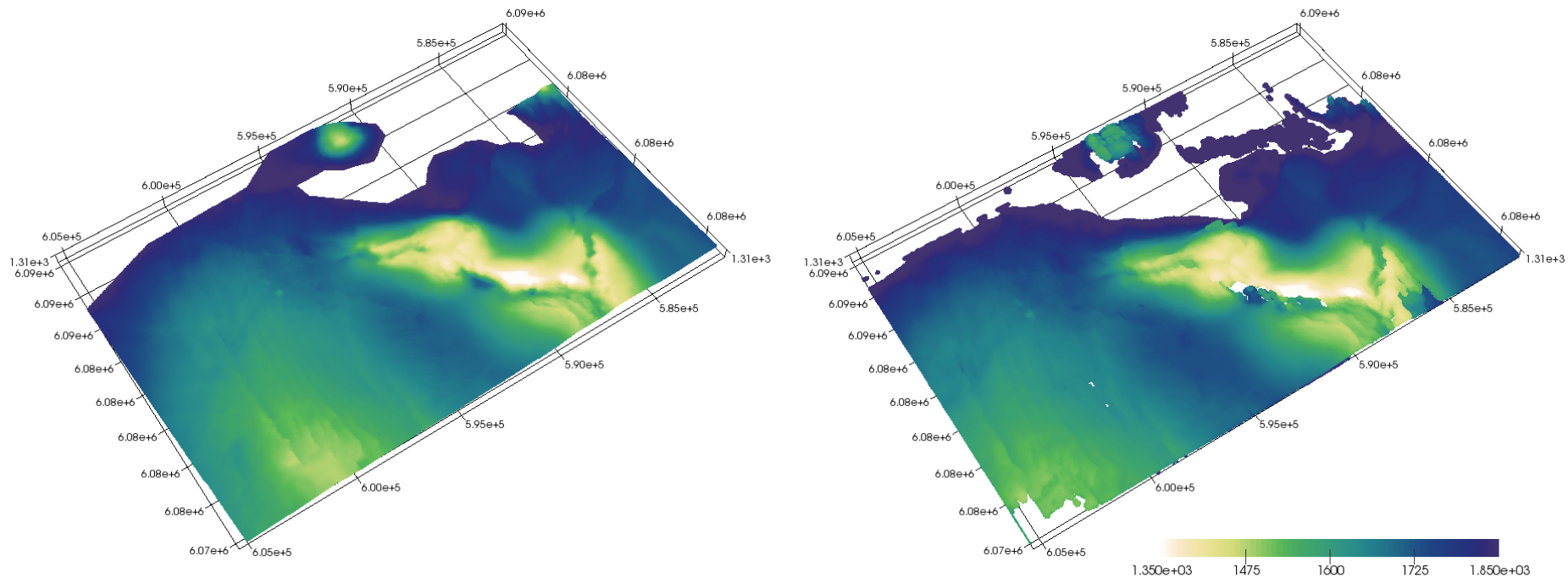
Good Fault Zone Detection

Salt Structure

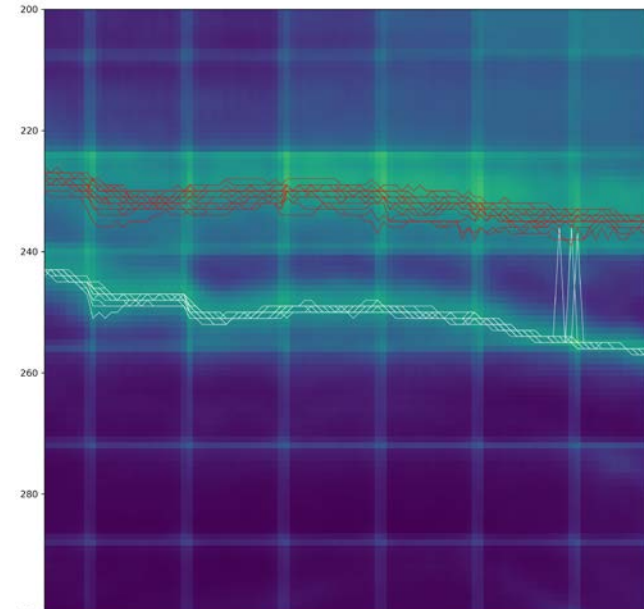
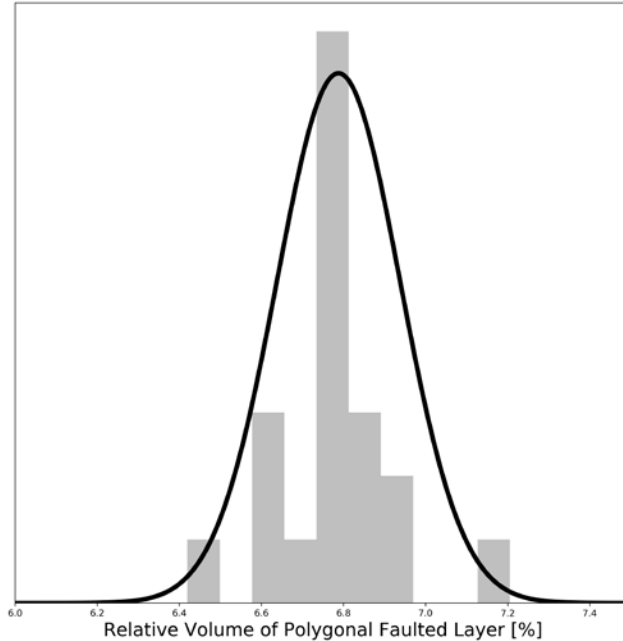


Same Interpreter as for Training Data (i.e. Mike)

Extracted Top Salt Surface Comparison



Polygonal Fault Volume Probabilistic Estimate



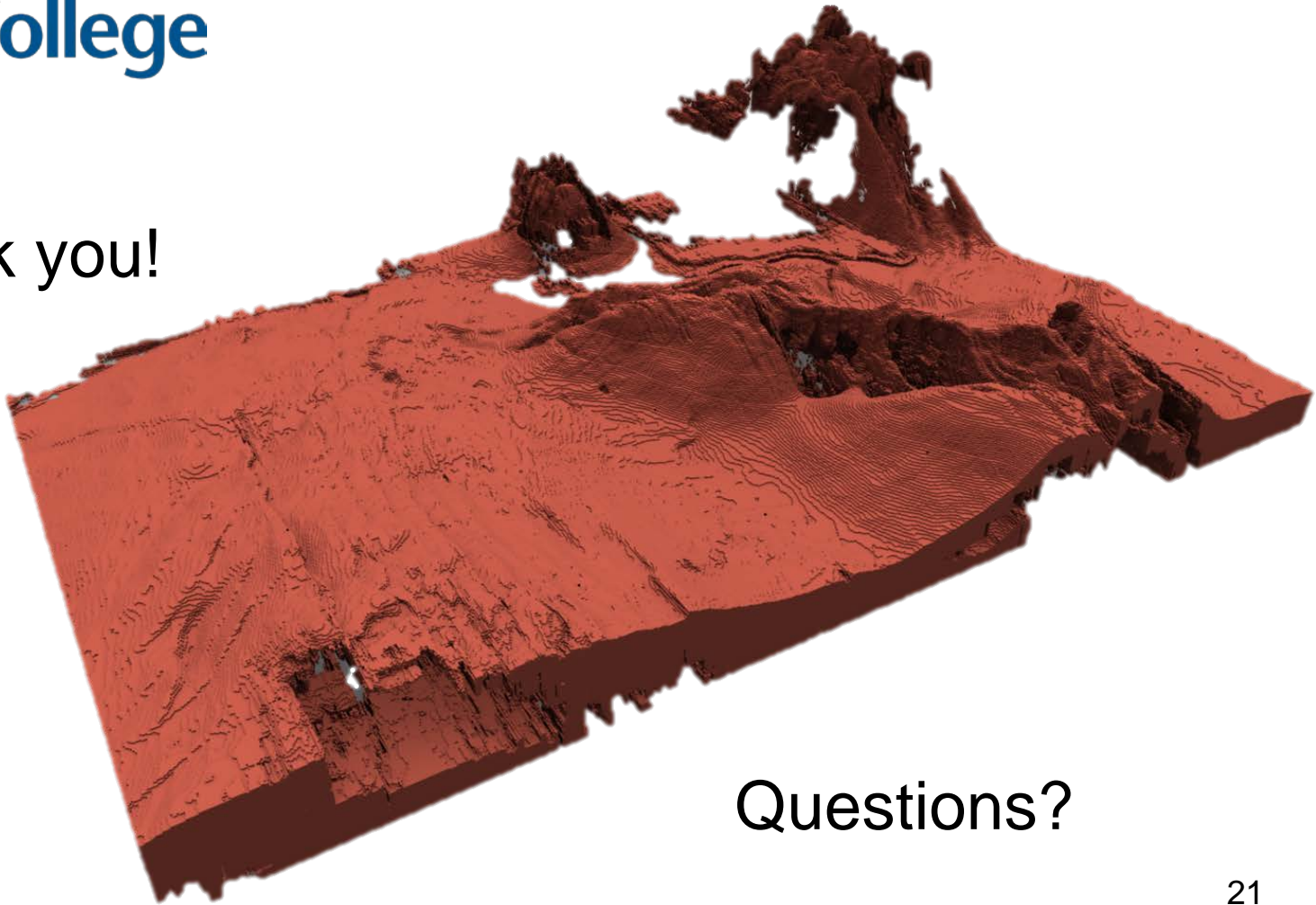
What did and what did not work? Open Challenges

- What did work?
 - Patch-based training better for small datasets, not enough data for full x/inline
 - Monte-Carlo Dropout *can* be applied to any neural network
 - Segnet provides good results
- What did not work?
 - U-Net not clear how big impact of skip connections is on uncertainty
 - MalenoV dataset too limited.
- Open Challenges:
 - Baseline dataset: Possibly this one?
 - How to deal with multiple interpretations?

Conclusions

- Two Types of Uncertainty: Epistemic and Aleatoric
- Traditional Neural Networks Provide no measure of model uncertainty (UQ on weights)
- Bayesian Neural Networks allow estimation of model uncertainty
- Dropout applied at test time can approximate posterior inference
- Bayesian Neural Networks allow good prediction on small datasets
- Allows Variance in predictions to be incorporated into
 - Decision making process
 - Data Acquisition Strategy

Thank you!



Questions?

Backup Slides